

nD-PointCloud

Netherlands eScience Center contributions

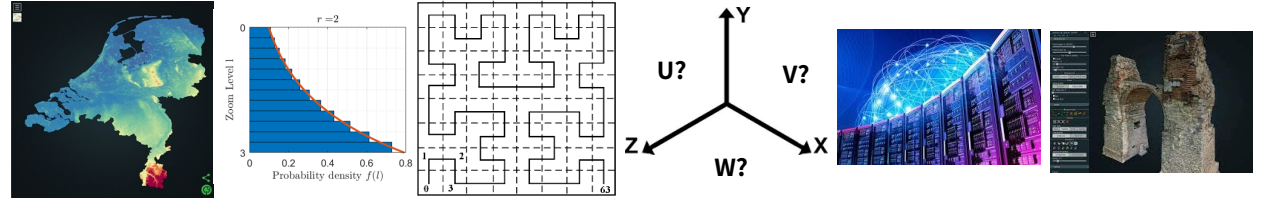
Thijs van Lankveld

netherlands
eScience center

End-of-Project Meeting 2024/11/12



Project Goals



Point clouds as primary representation of spatio-temporal features

Scientific questions

- Will adding a continuous “importance” value improve processes?
- Will organizing points along space-filling curves help efficient processing?
- How can high-dimensional data be handled without performance drops?

eScience challenges

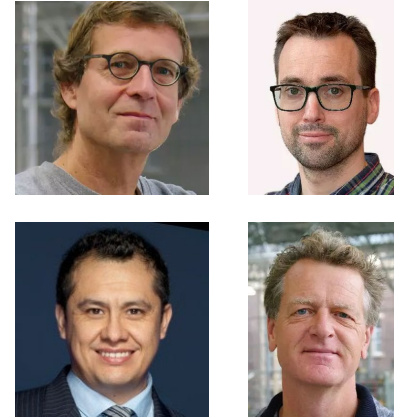
- Enabling HPC to handle innovations and scale of PC data (presented next)
- Updating PC viewer to modern standards
- Processing progressive AHN data for viewing



People involved

TU Delft

- Peter van Oosterom, Martijn Meijers, Vitali Diaz Mercado
- Edward Verbree

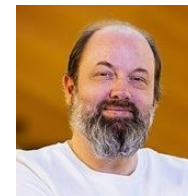


NLeSC

- Thijs van Lankveld, Maarten van Meersbergen, Nauman Ahmed
- Peter Kok, Ewan Cahen, Dusan Mijatovic, Sarah Alidoost

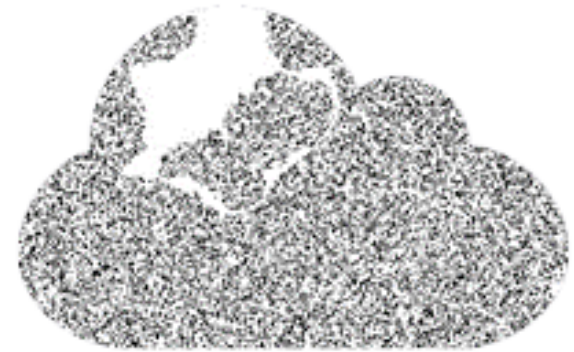
External

- Markus Schütz (Potree)
- Fedor Baart, Maarten Pronk (Deltares)



Data Storage Options

- LAS/LAZ
- EPT
- COPC
- EPT-COPC hybrid
- VPC



LAS/LAZ

- Metadata in header
- Various point formats
- Point coordinates and attributes
 - Good compression
- Variable Length Records

Table 21: Point Data Record Format 10

Item	Format	Size	Required
X	long	4 bytes	*
Y	long	4 bytes	*
Z	long	4 bytes	*
Intensity	unsigned short	2 bytes	
Return Number	4 bits (bit 0 – 3)	4 bits	*
Number of Returns (given pulse)	4 bits (bit 4 – 7)	4 bits	*
Classification Flags	4 bits (bits 0 – 3)	4 bits	
Scanner Channel	2 bits (bits 4-5)	2 bits	*
Scan Direction Flag	1 bit (bit 6)	1 bit	*
Edge of Flight Line	1 bit (bit 7)	1 bit	*
Classification	unsigned char	1 byte	*
User Data	unsigned char	1 byte	
Scan Angle	short	2 bytes	*
Point Source ID	unsigned short	2 bytes	*
GPS Time	double	8 bytes	*
Red	unsigned short	2 bytes	*
Green	unsigned short	2 bytes	*
Blue	unsigned short	2 bytes	*
NIR	unsigned short	2 bytes	*
Wave Packet Descriptor Index	unsigned char	1 byte	*
Byte offset to waveform data	unsigned long long	8 bytes	*
Waveform packet size in bytes	unsigned long	4 bytes	*
Return Point Waveform Location	float	4 bytes	*
X(t)	float	4 bytes	*
Y(t)	float	4 bytes	*
Z(t)	float	4 bytes	*



https://www.asprs.org/wp-content/uploads/2010/12/LAS_1_4_r13.pdf



Entwine Point Tile

EPT metadata

```
├─ ept.json
├─ ept-data
│  └─ 0-0-0-0.laz
├─ ept-hierarchy
│  └─ 0-0-0-0.json
└─ ept-sources
   ├─ list.json
   └─ 0.json
```

EPT point cloud tiles (laz)

```
{
  "0-0-0-0": 65341,
  "1-0-0-0": 438,
  "2-0-1-0": 322,
  "1-0-0-1": 56209,
  "2-0-1-2": 4332,
  "2-1-1-2": 20300,
  "2-1-1-3": 64020,
  "3-2-3-6": 32004,
  "4-4-6-12": 1500,
  "4-5-6-13": 2400,
  "3-3-3-7": 542,
  "1-0-1-0": 30390,
  "2-1-2-0": 2300,
  "1-1-1-1": 2303
}
```



<https://entwine.io/en/latest/entwine-point-tile.html>



Cloud Optimized Point Cloud

EPT metadata

```

├─ ept.json
├─ ept-data
│   └─ 0-0-0-0.laz
├─ ept-hierarchy
│   └─ 0-0-0-0.json
└─ ept-sources
    ├─ list.json
    └─ 0.json
    
```

COPC file (laz)

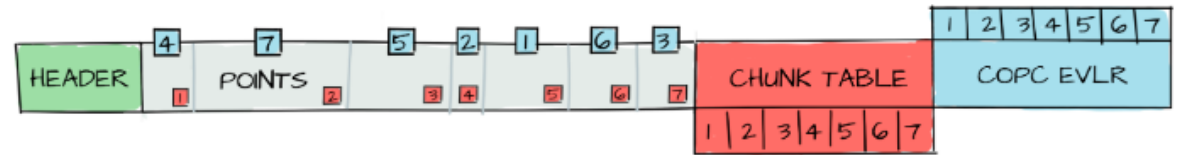
point clouds + octree metadata

accessible chunks

EPT point cloud tiles (laz)

```

{
  "0-0-0-0": 65341,
  "1-0-0-0": 438,
  "2-0-1-0": 322,
  "1-0-0-1": 56209,
  "2-0-1-2": 4332,
  "2-1-1-2": 20300,
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  "3-3-3-7": 542,
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  "2-1-2-0": 2300,
  "1-1-1-1": 2303
}
    
```



COPC.io
Cloud Optimized Point Cloud

<https://copc.io/>



EPT-COPC hybrid

EPT metadata

```

├─ ept.json
├─ ept-data
│   └─ 0-0-0-0.laz
├─ ept-hierarchy
│   └─ 0-0-0-0.json
└─ ept-sources
    ├── list.json
    └─ 0.json
    
```

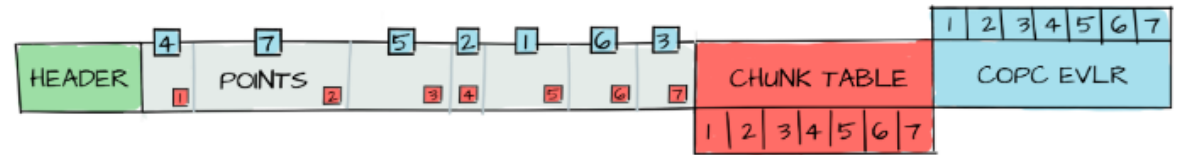
Costly to transfer many files

Intractable to have massive-TB file

COPC point cloud chunks

```

{
  "0-0-0-0": 65341,
  "1-0-0-0": 438,
  "2-0-1-0": 322,
  "1-0-0-1": 56209,
  "2-0-1-2": 4332,
  "2-1-1-2": 20300,
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  "4-4-6-12": 1500,
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  "3-3-3-7": 542,
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  "1-1-1-1": 2303
}
    
```



Virtual Point Cloud

- Metadata for multiple LAS/LAZ/COPC files
 - Similar to EPT metadata
- STAC API ItemCollection
- Referenced by URL: remote data enabled
- Implemented in PDAL wrench
 - Module in QGIS 3.32*
 - Depends on PDAL dev, GDAL dev



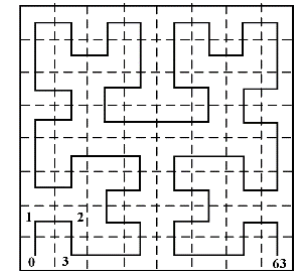
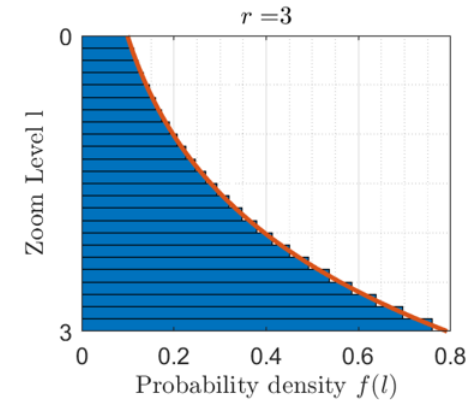
*in Ubuntu: use flatpak install



<https://www.lutraconsulting.co.uk/blog/2023/06/08/virtual-point-clouds/>

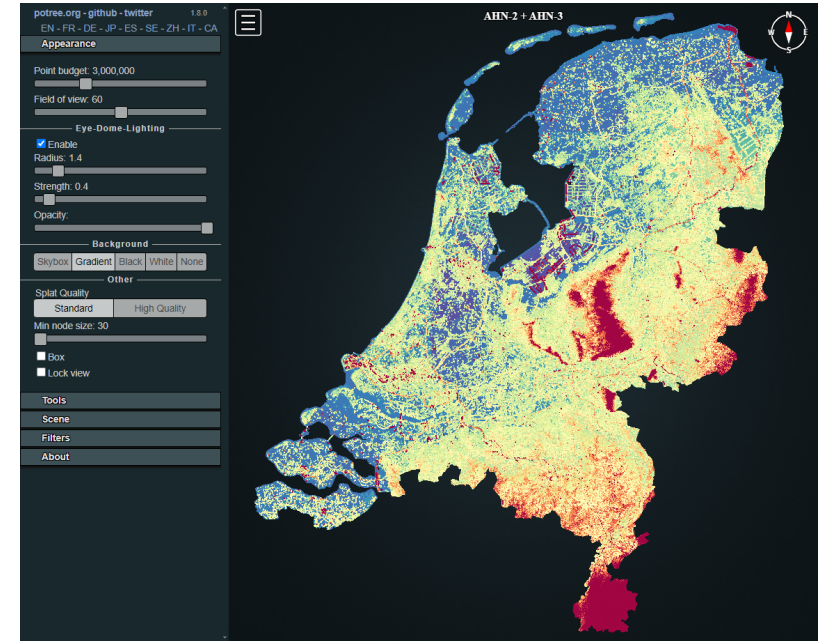
Data Storage Considerations

- File size vs. transfer cost
- Local vs. remote
- Additional point features
 - cLol
 - Changes forward & backward.
- Octree vs. space-filling curve
- File storage vs. other storage options



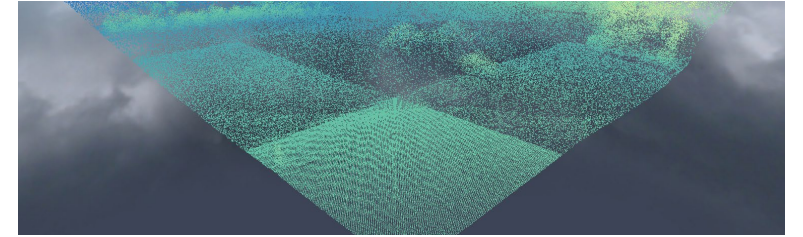
Potree

- Developed by Markus Schütz (TU Wien)
- Point cloud viewer
- Open source (2-clause BSD)
- Over 1k forks
- Implemented in JavaScript
 - WebGL renderer (to become WebGPU)
 - Depends on Node.js, Gulp

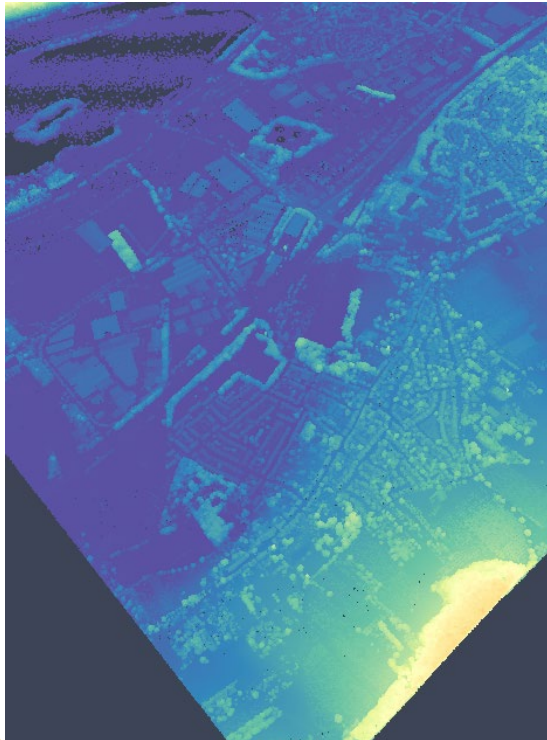


<https://github.com/potree/potree>

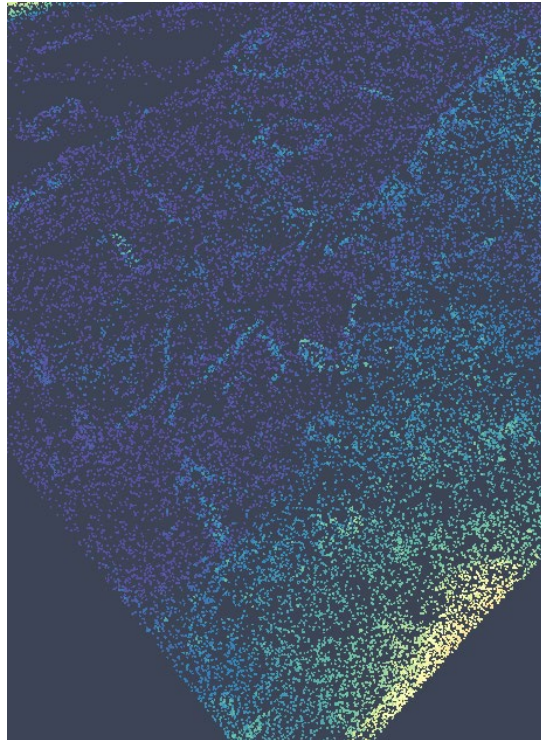
Potree: cLol Rendering



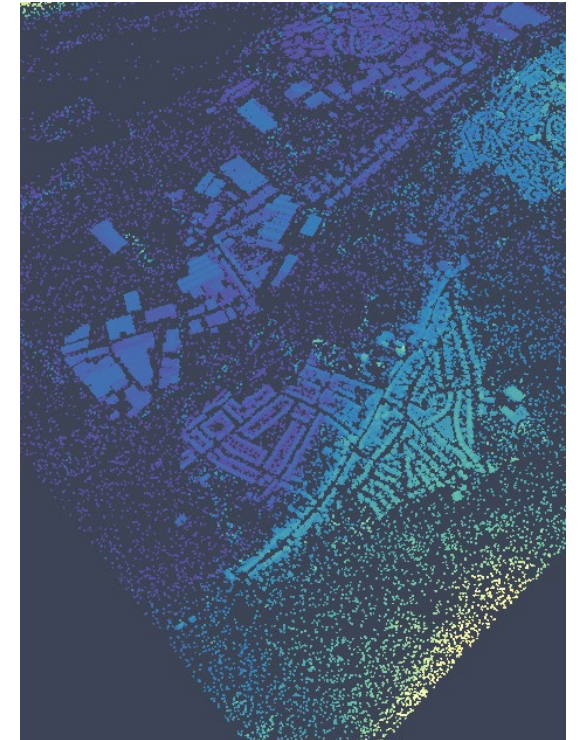
Base



cLol



Weighted cLol



Potree: VPC loader

- Developed by Netherlands eScience Center
- Potree loader module for VPC
- Challenges
 - Limited to COPC data (raw LAS/LAZ not natively supported)
 - Potree has many internal assumptions on 8-child structure
 - File extension conflict with Veesus PC Arena 4D



Converting AHN to COPC / VPC

ronna.tudelft.nl: Dell PowerEdge R7525

- Processors: 2x AMD EPYC 7443
- Cores: 2x 24
- Threads: 96*
- Speed: 2.85GHz
- RAM: 512GB (RDIMM)
- Scratch storage (input): 19.2TB SSD SATA
- Bulk storage (output): 60TB SAS, 7.2k rpm, RAID-5



*only 1-4 threads used: memory is bottleneck



Conversion Results

AHN 3

- Input files: 1374
- Input size: 2.4 TB
- Processing time (wc): 14d, 5h
- Output files: 382
- Output size: 3.1 TB

AHN 4

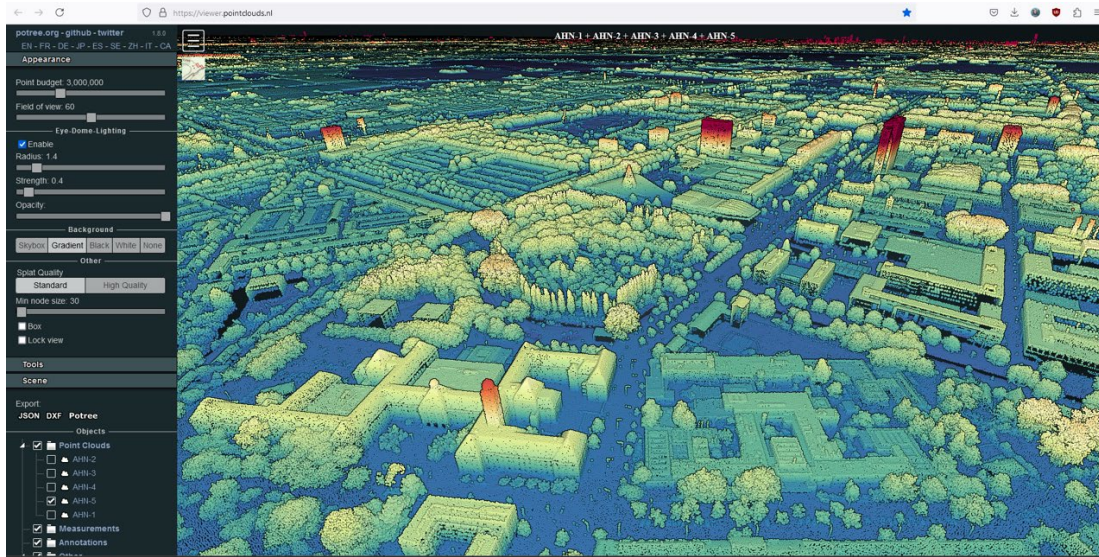
- Input files: 1381
- Input size: 6.1 TB
- Processing time (wc): 26d*
- Output files: 381
- Output size: 5.1 TB

*estimated due to several large interruptions



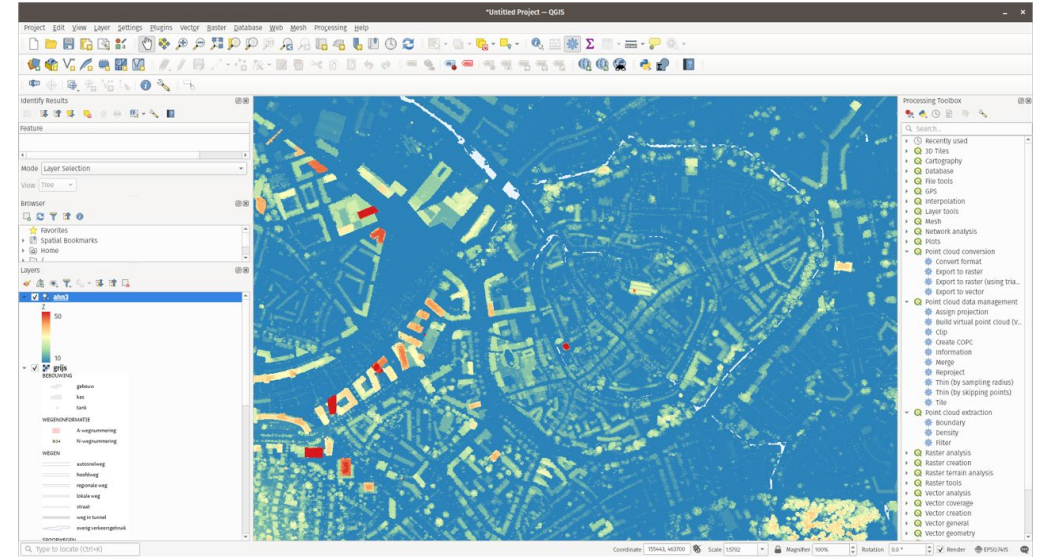
Viewing AHN

Potree



<https://viewer.pointclouds.nl/>

QGIS



to be released...



Conclusions

eScience contributions

- Exploring options for data storage
- Adapting Potree with cLoI rendering and VPC loader
- Converting AHN 3-4 to COPC and VPC
- Converting AHN 1-5 to .potree files (presented next)



Let's keep
in touch



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