

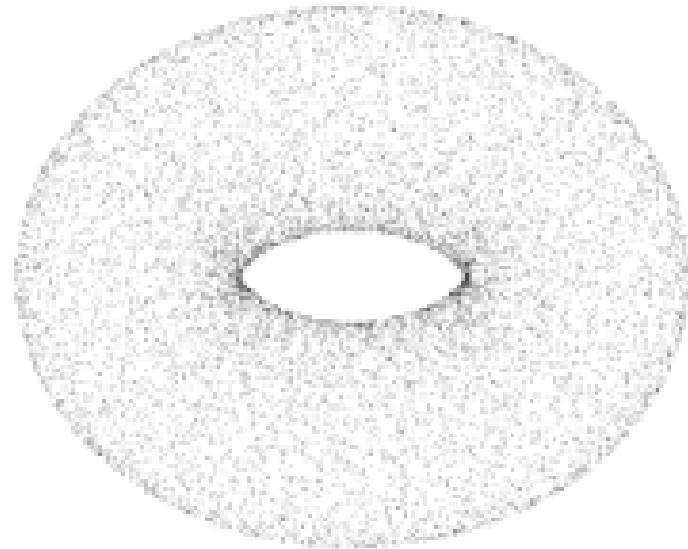
PotreeConverterMPI: An MPI implementation of PotreeConverter

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eScience center

Pointcloud



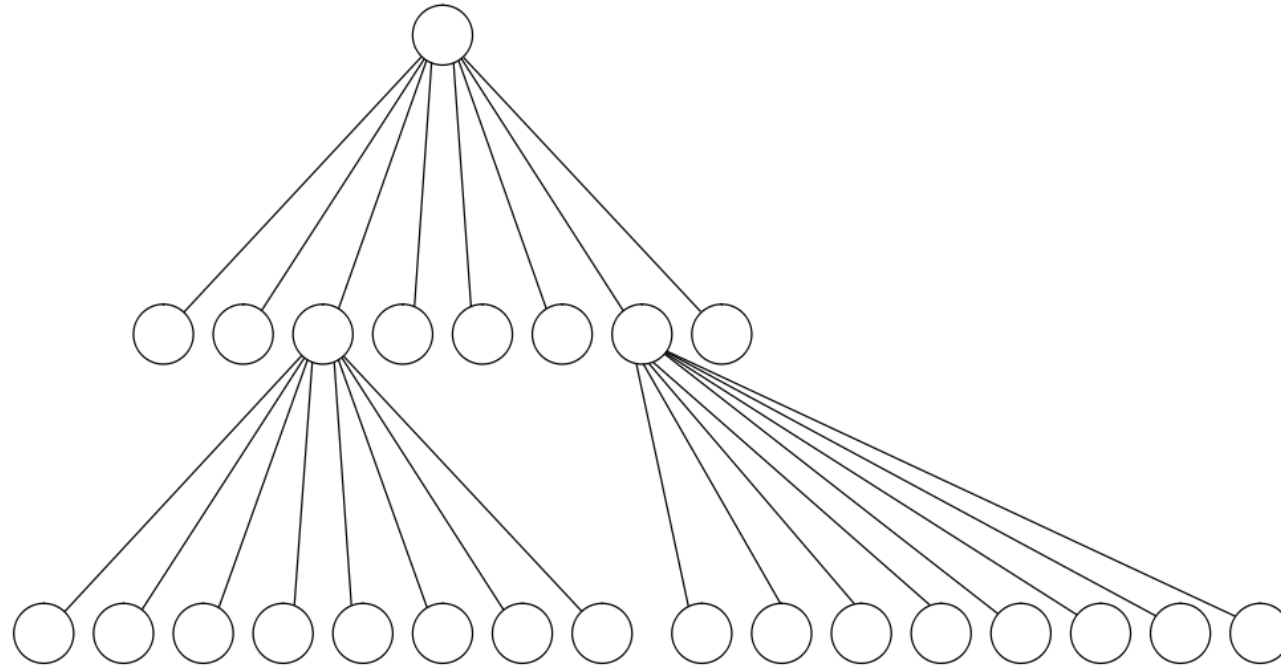
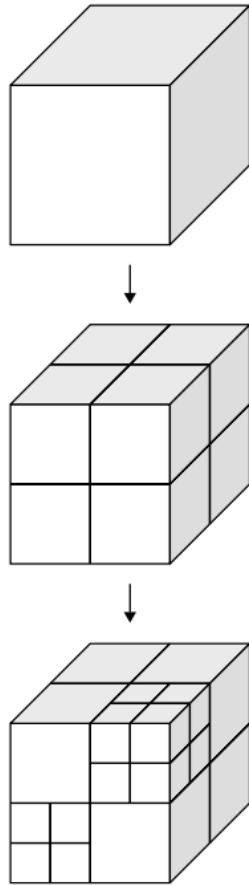
Pointcloud format

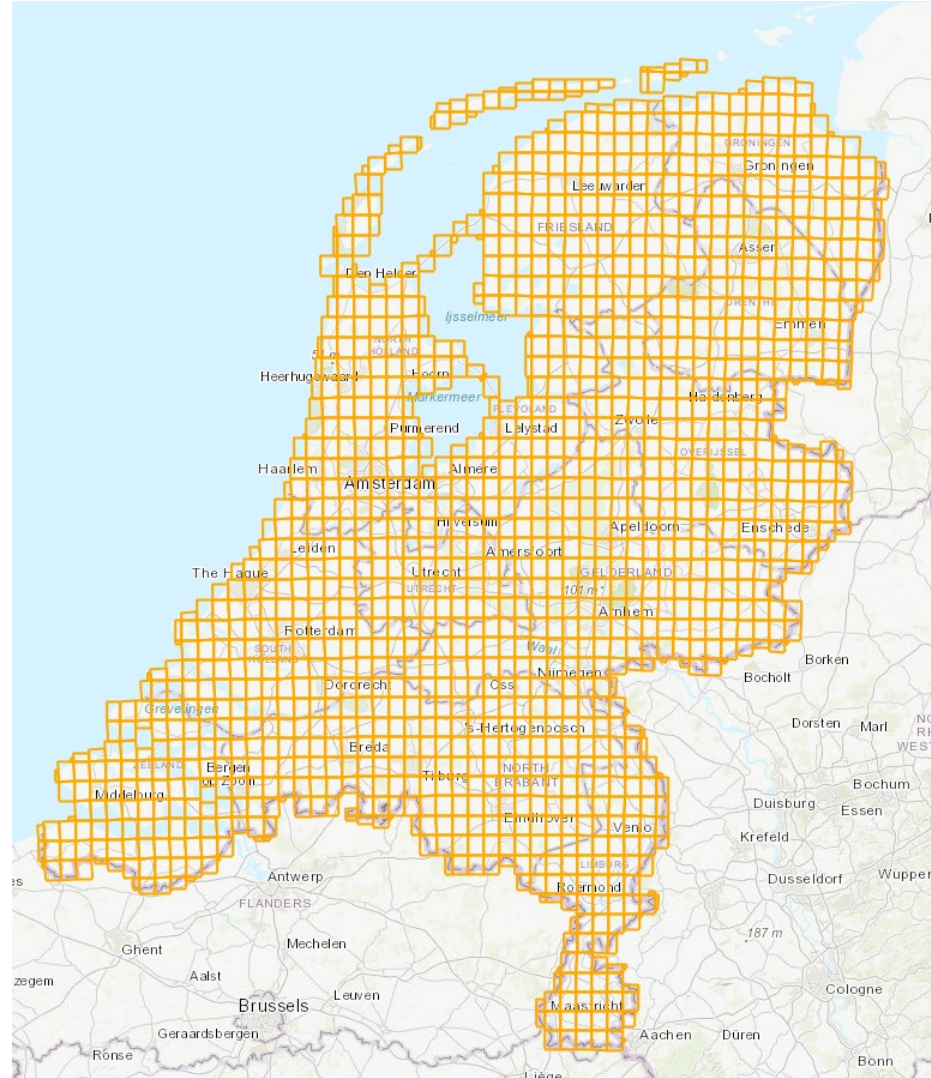
Table 12: Point Data Record Format 3

Item	Format	Size	Required
X	long	4 bytes	*
Y	long	4 bytes	*
Z	long	4 bytes	*
Intensity	unsigned short	2 bytes	
Return Number	3 bits (bits 0, 1, 2)	3 bits	*
Number of Returns (given pulse)	3 bits (bits 3, 4, 5)	3 bits	*
Scan Direction Flag	1 bit (bit 6)	1 bit	*
Edge of Flight Line	1 bit (bit 7)	1 bit	*
Classification	unsigned char	1 byte	*
Scan Angle Rank (-90 to +90) – Left side	char	1 byte	*
User Data	unsigned char	1 byte	
Point Source ID	unsigned short	2 bytes	*
GPS Time	double	8 bytes	*
Red	unsigned short	2 bytes	*
Green	unsigned short	2 bytes	*
Blue	unsigned short	2 bytes	*



Octree representation of pointcloud





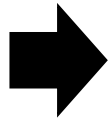
New developments

“NUVIEW announced to launch 20 satellites with laser scanners to collect global elevation model (and repeat this every year), aimed for accuracy USGS QL2 (2 pnts/m², 10 cm vertical accuracy). Ok, with total surface area of the Earth of about 509.600.000 km² of which area of land: 148.326.000 km², that would be every year $2 \times 148.326.000.000.000 = 296.652.000.000.000$ points. To compare AHN2 has about 640.000.000.000 points, So, this new dataset would be about 500 times larger.”

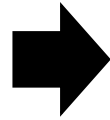


Potree

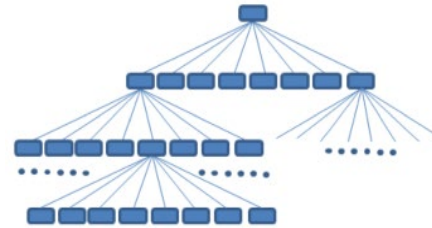
LAZ/LAS



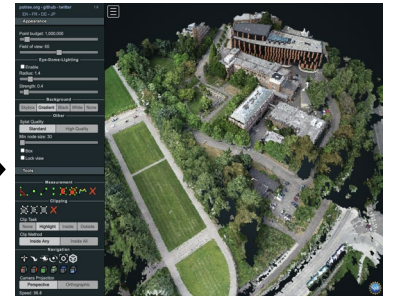
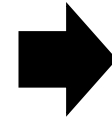
Converter



Octree



Viewer

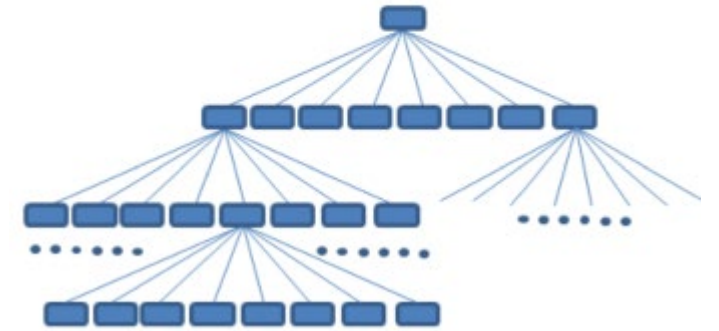
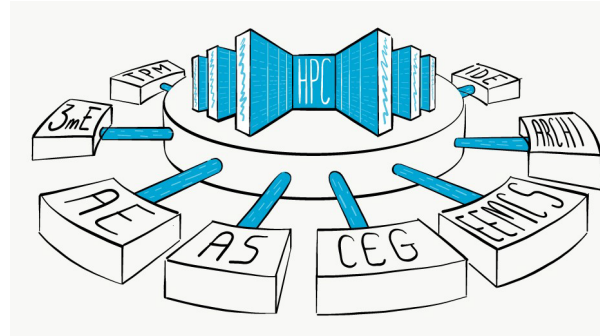


PotreeConverterMPI

Nauman Ahmed, Thijs van Lankveld, Martijn Meijers, Peter van Oosterom, Vitali Diaz, Edward Verbree



PotreeConverter on DelftBlue

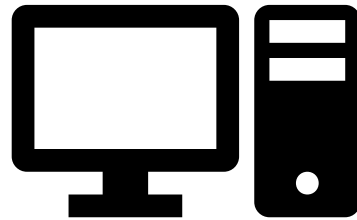


Problems



2.

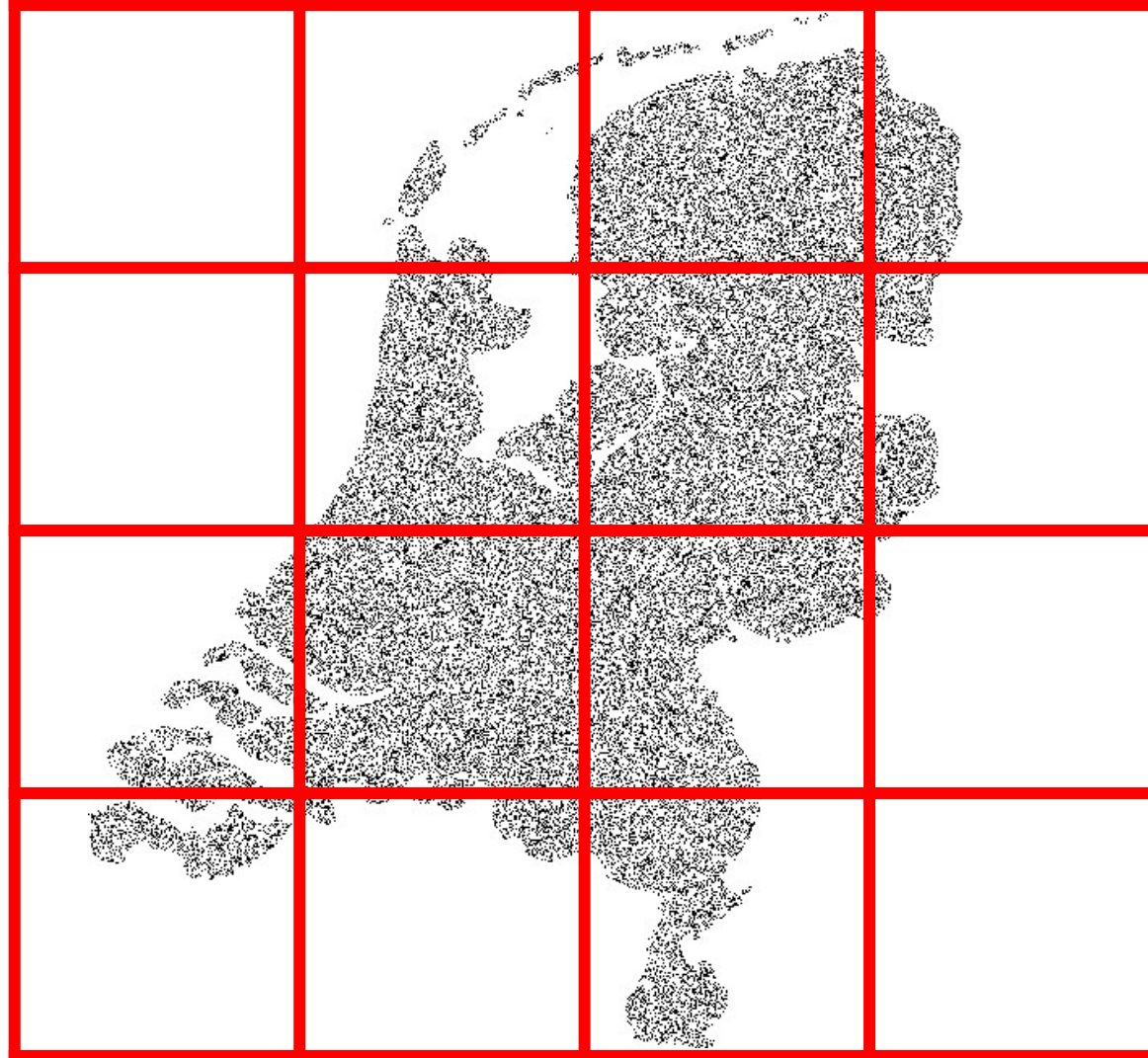
Original implementation is for single compute node



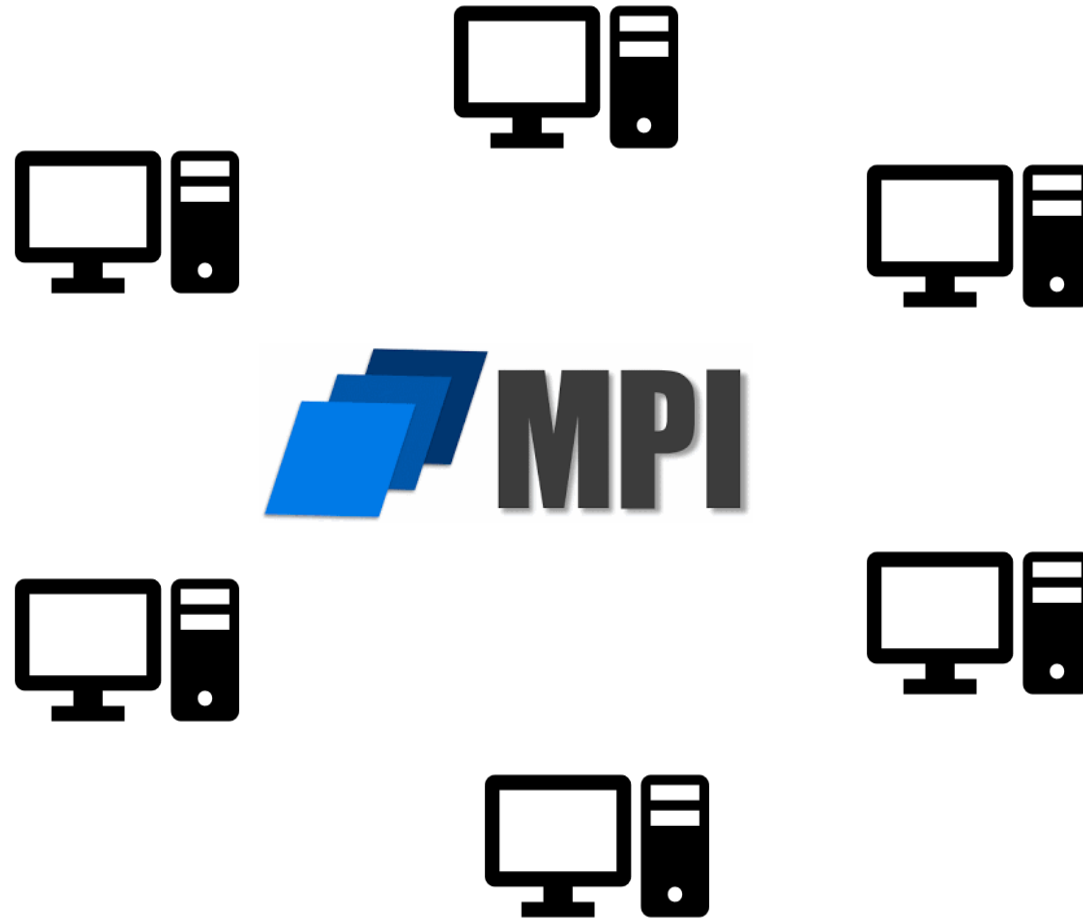
Solutions



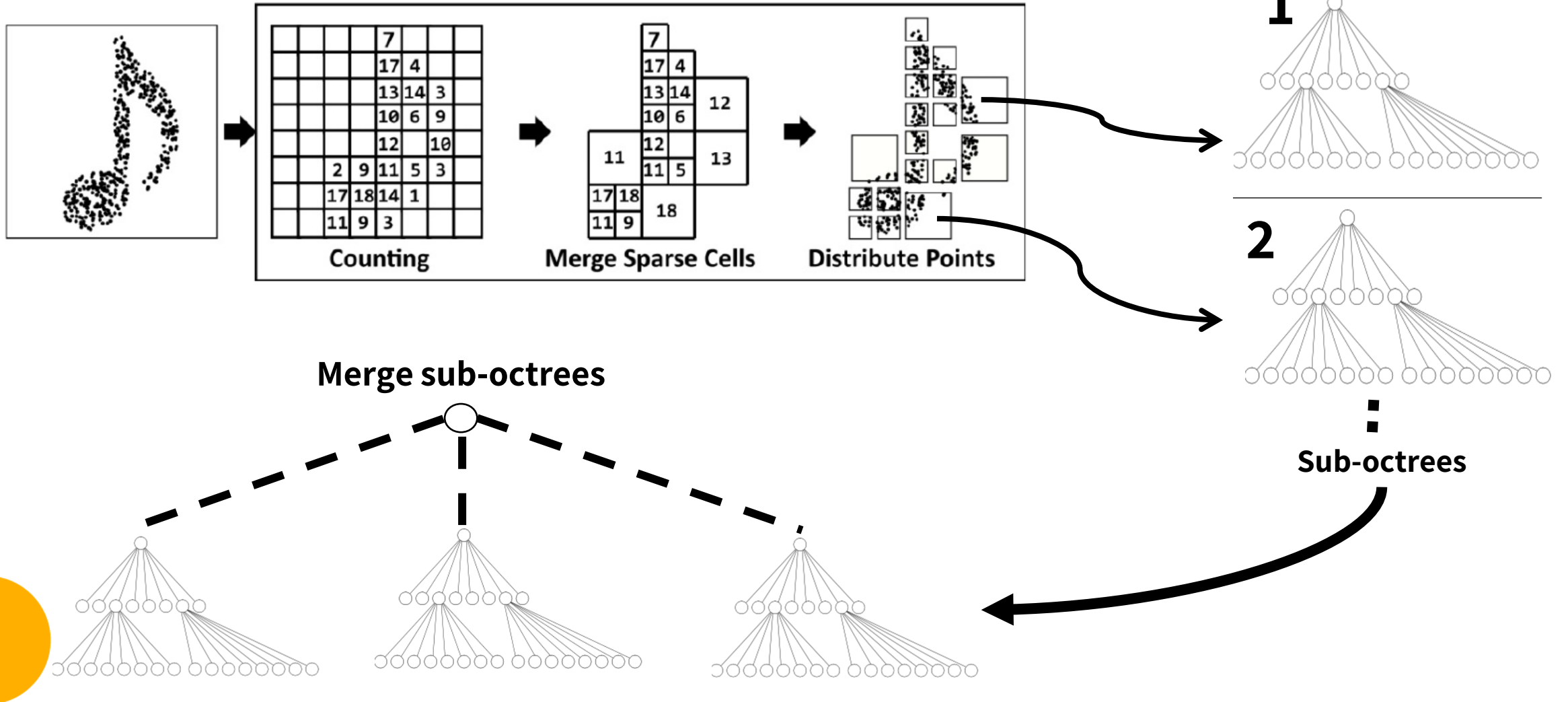
1. Partition



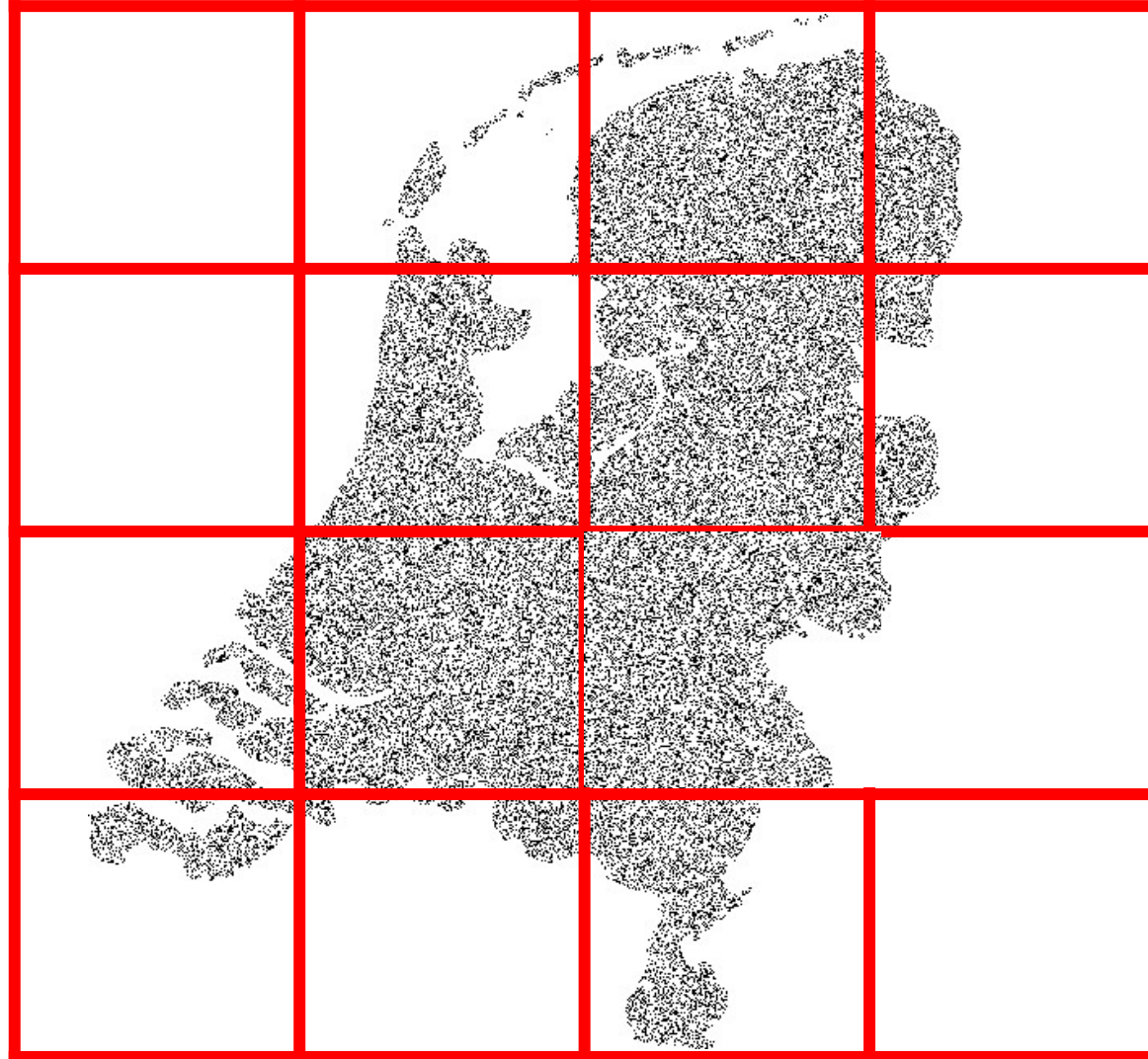
2. MPI



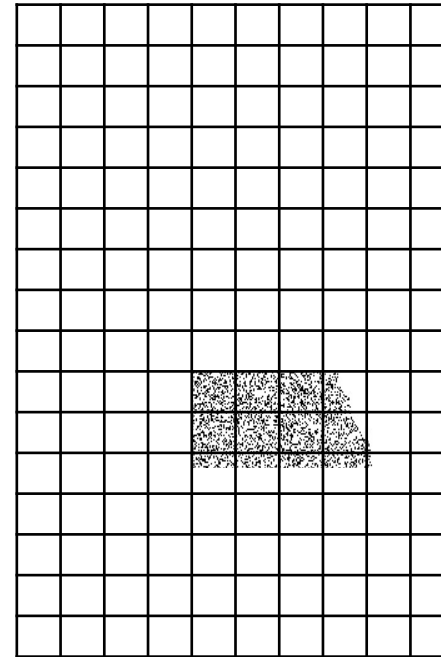
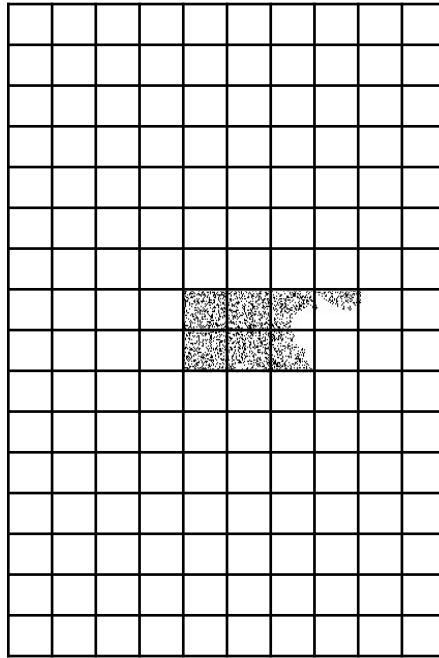
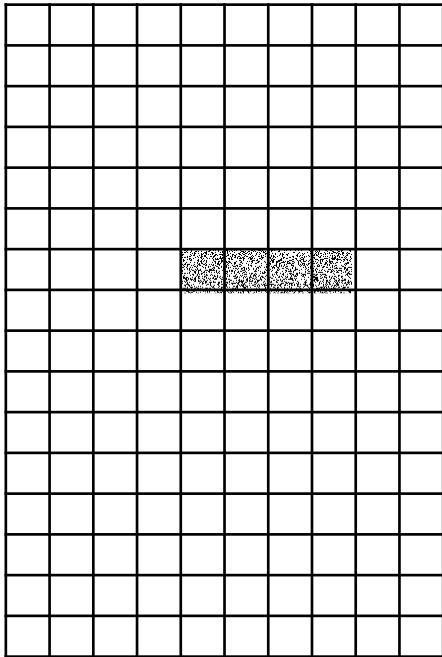
PotreeConverter



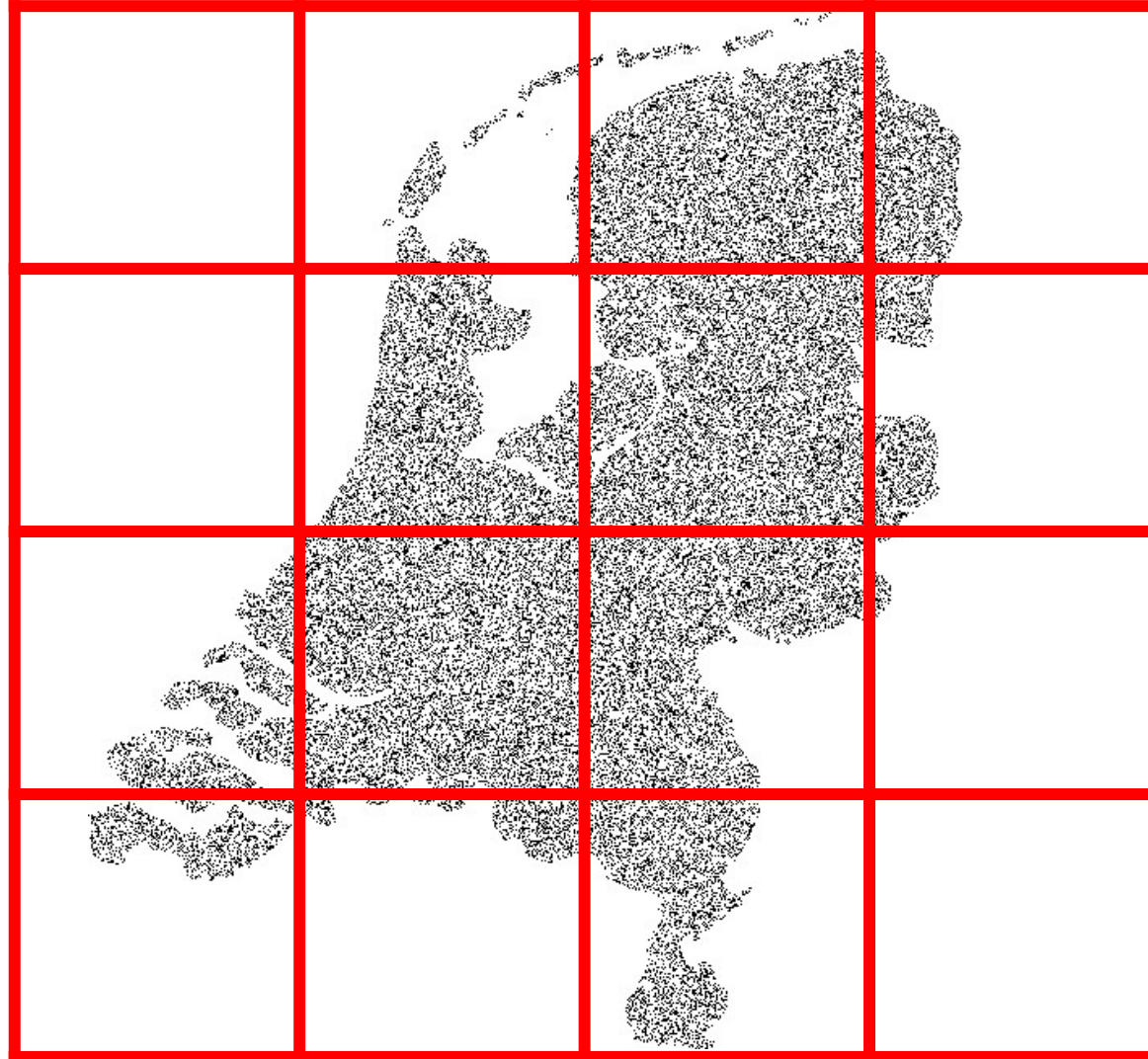
PotreeConverterMPI Counting



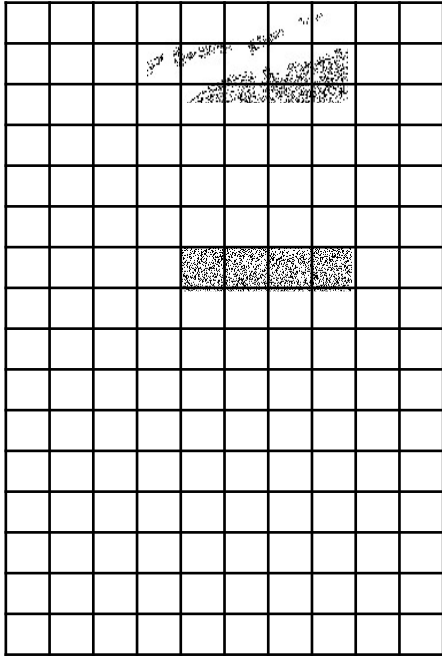
PotreeConverterMPI Counting



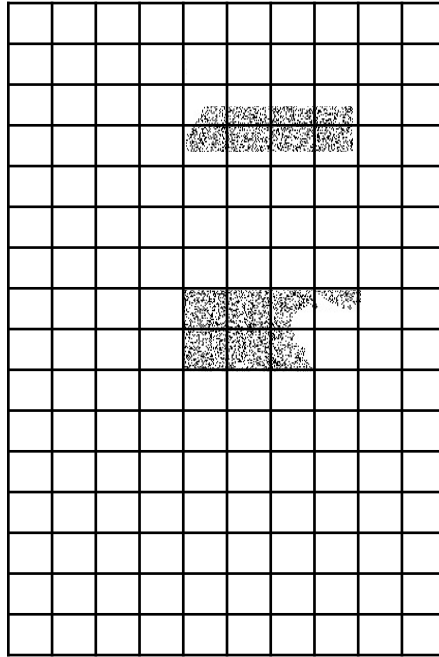
PotreeConverterMPI Counting



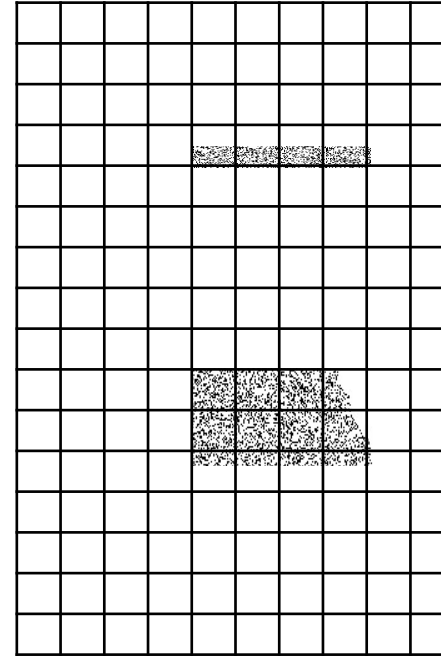
PotreeConverterMPI Counting



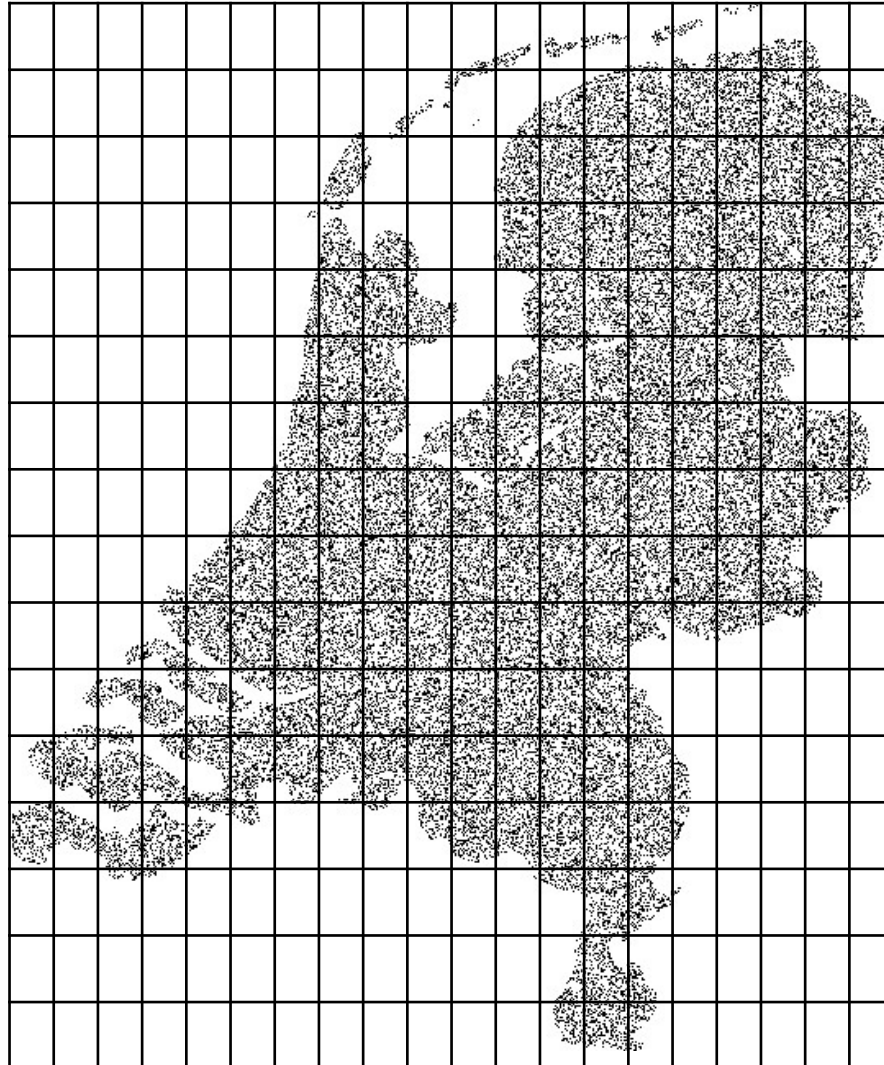
+



+

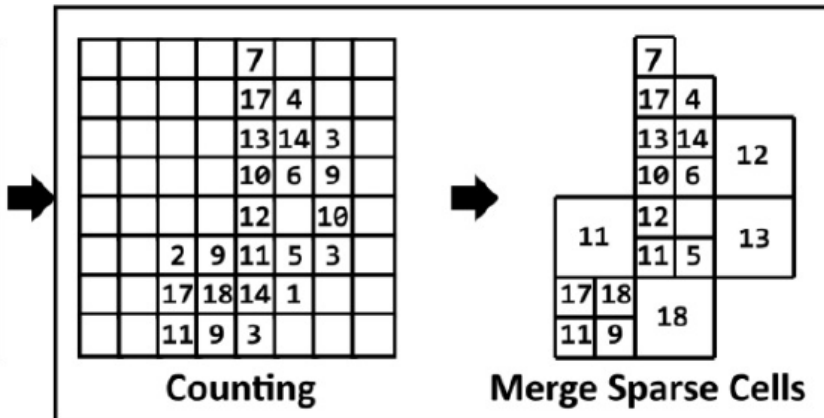


PotreeConverterMPI Counting



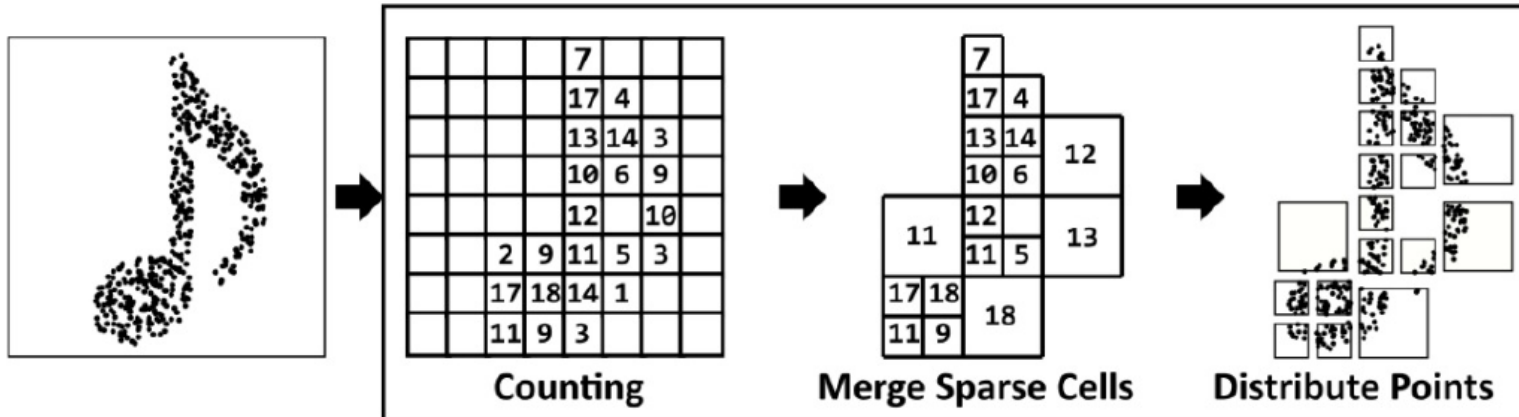
PotreeConverterMPI erge sparse cells

Input



PotreeConverterMPI Distribution

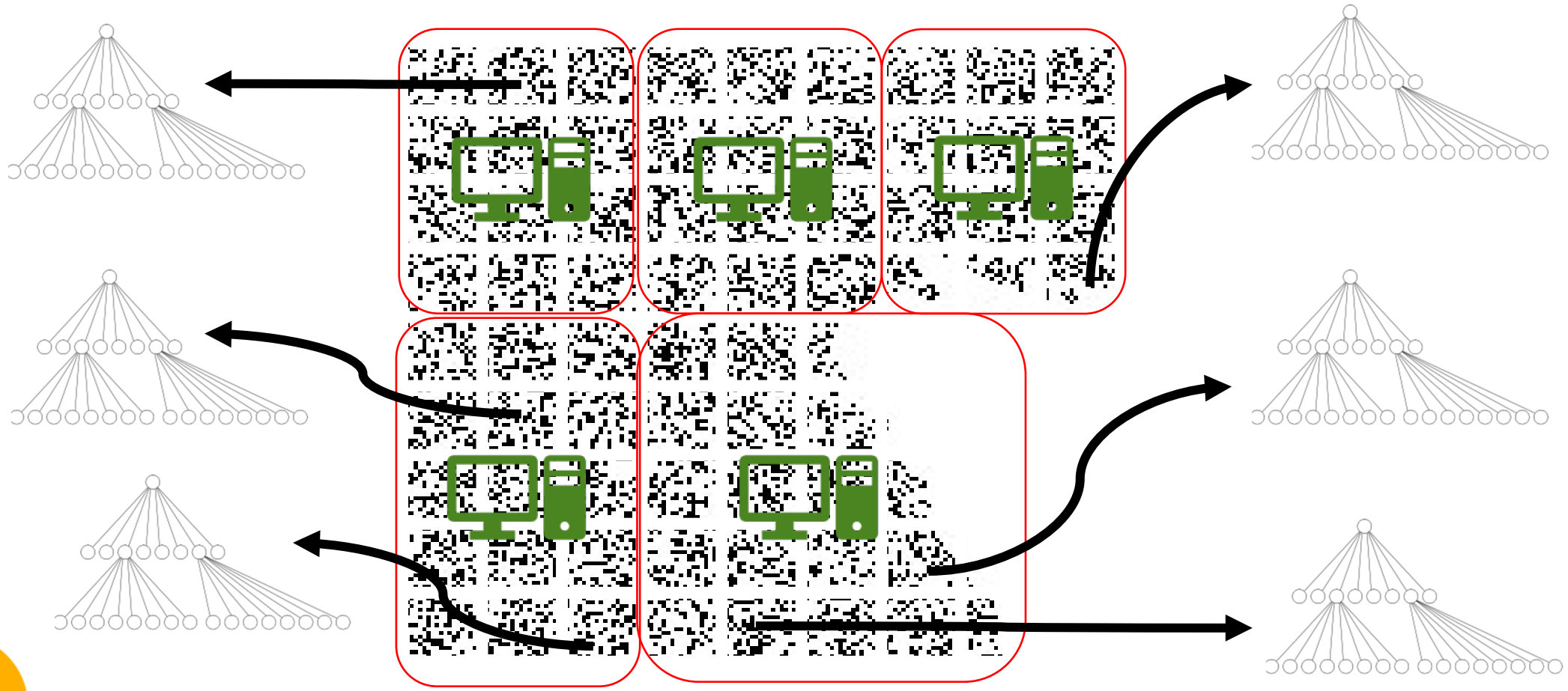
Input



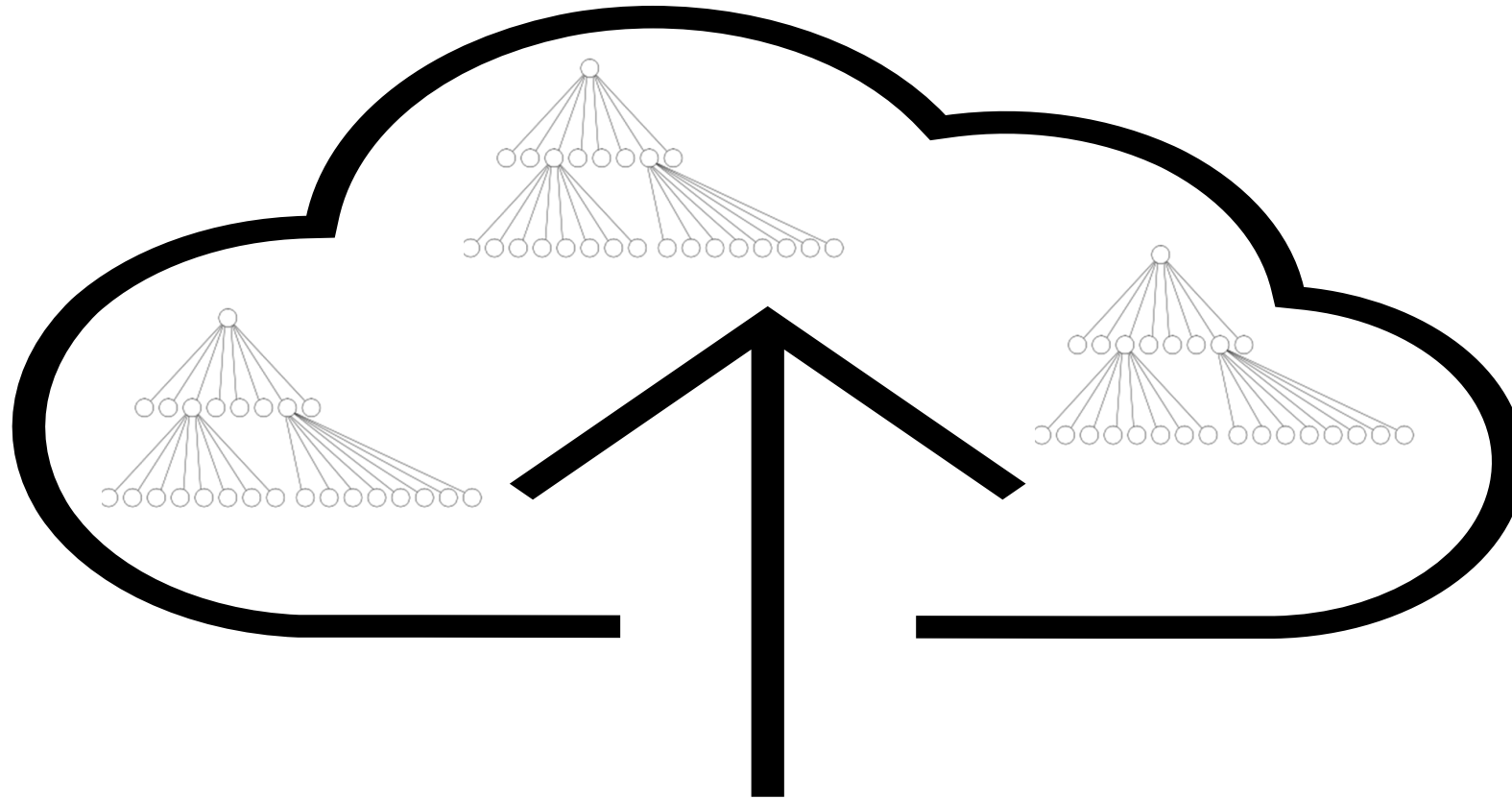
PotreeConverterMPI Distribution



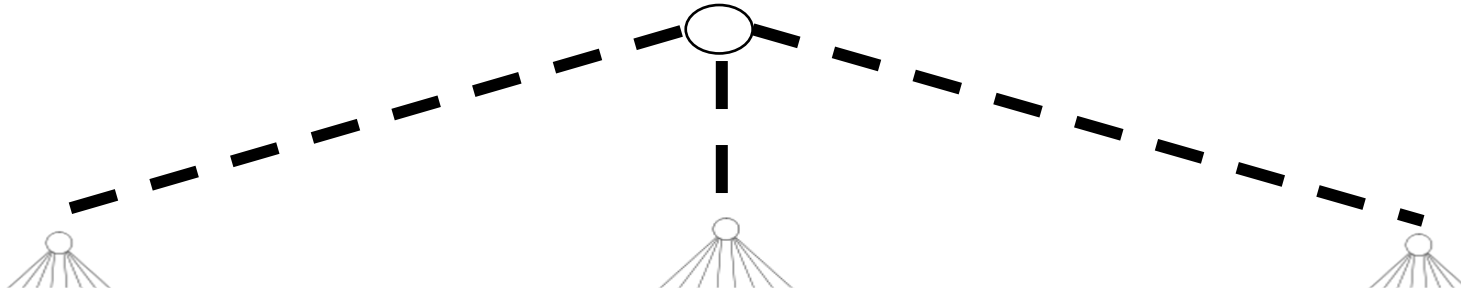
PotreeConverterMPI Indexing



PotreeConverter MPI Distribution & Indexing

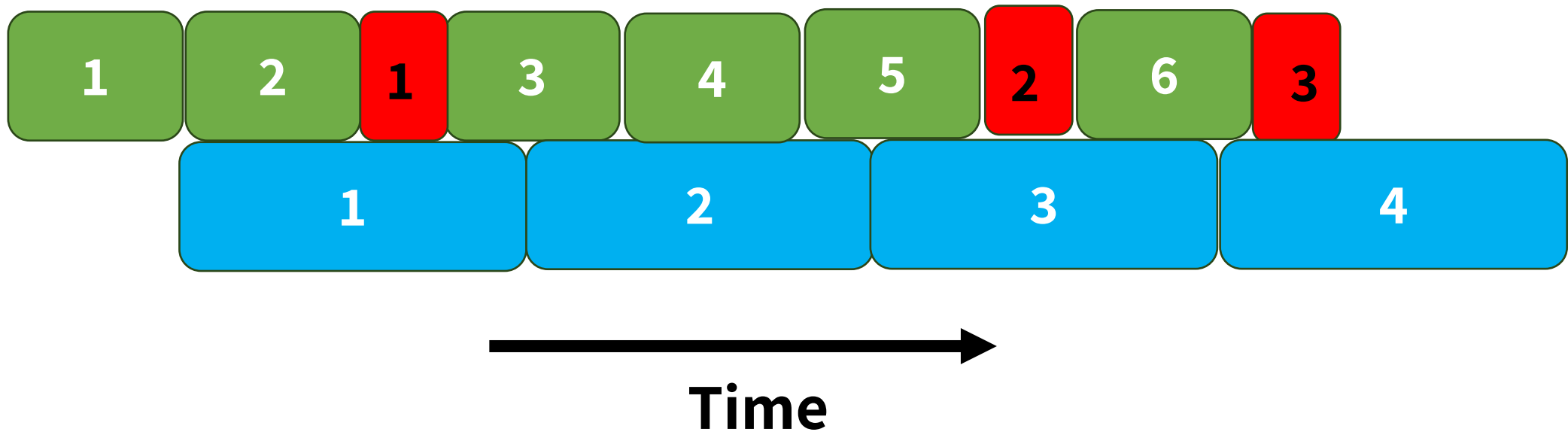


Merge sub-octrees




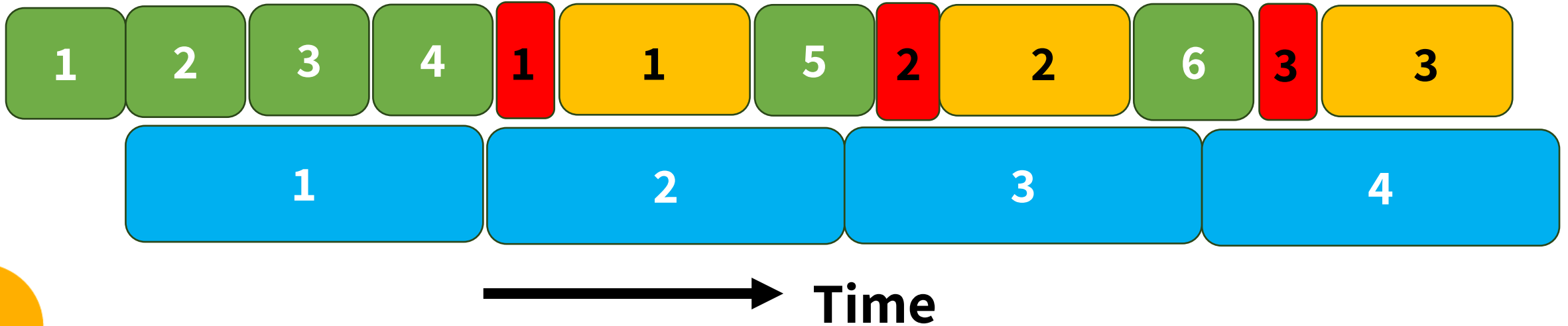
Partition loader/unloader script

- Copy a partition
- Remove partition
- Counting



Partition loader/unloader script

-  Copy a partition
-  Remove partition
-  Move partial output to “BIG” storage
-  Distribution and Indexing



Performance

- Converted AHN3 on 20 nodes of Delftblue. 48 threads per node.

Node Category	Number	Cores	CPU/GPU	RAM	SSD
Compute 1	218	48	2x Intel XEON E5-6248R 24C 3.0GHz	185 GB	150 GB
Compute 2	90	64	2x Intel Xeon E5- 6448Y 32C 2.1GHz	250 GB	360 GB
Fat type-a	6	48	2x Intel XEON E5-6248R 24C 3.0GHz	750 GB	150 GB
Fat type-b	4	48	2x Intel XEON E5-6248R 24C 3.0GHz	1500 GB	150 GB

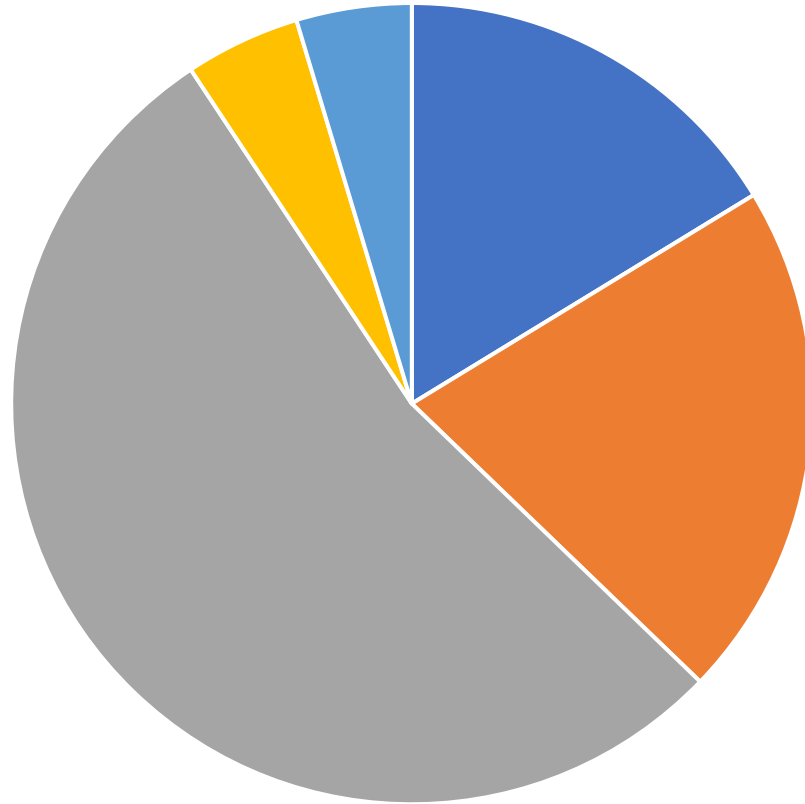


Performance

- ===== STATS =====
#points: 557'915'228'142
#input files: 1'370
sampling method: poisson
input file size: 14'548.8GB
duration: 150'155.039s (41 hours)
throughput (points/s) 3.7M



Performance



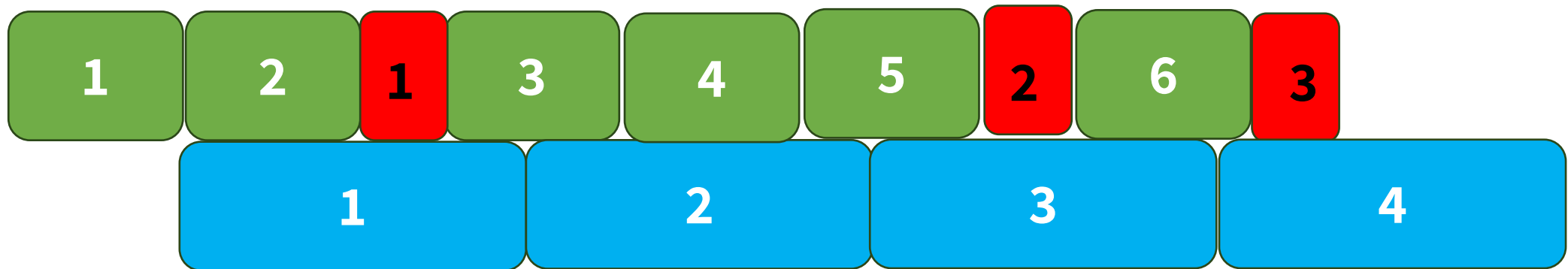
■ Counting (16%) ■ Distribution(18.6%) ■ Indexing(55%) ■ Output(4.5%) ■ Merging(4.5%)



Performance





- Perfect overlap in copying/removing data and processing in counting phase

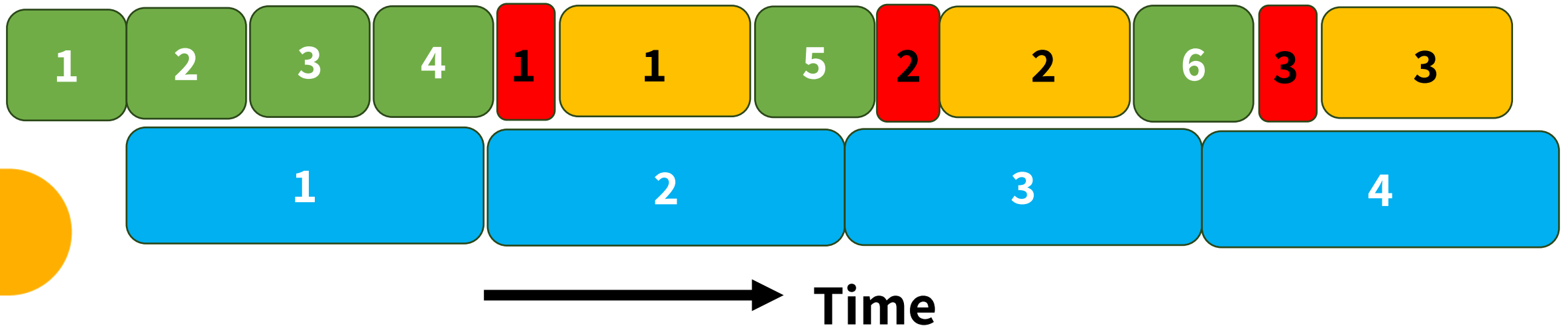
-  **Copy a partition**
-  **Remove partition**
-  **Counting**



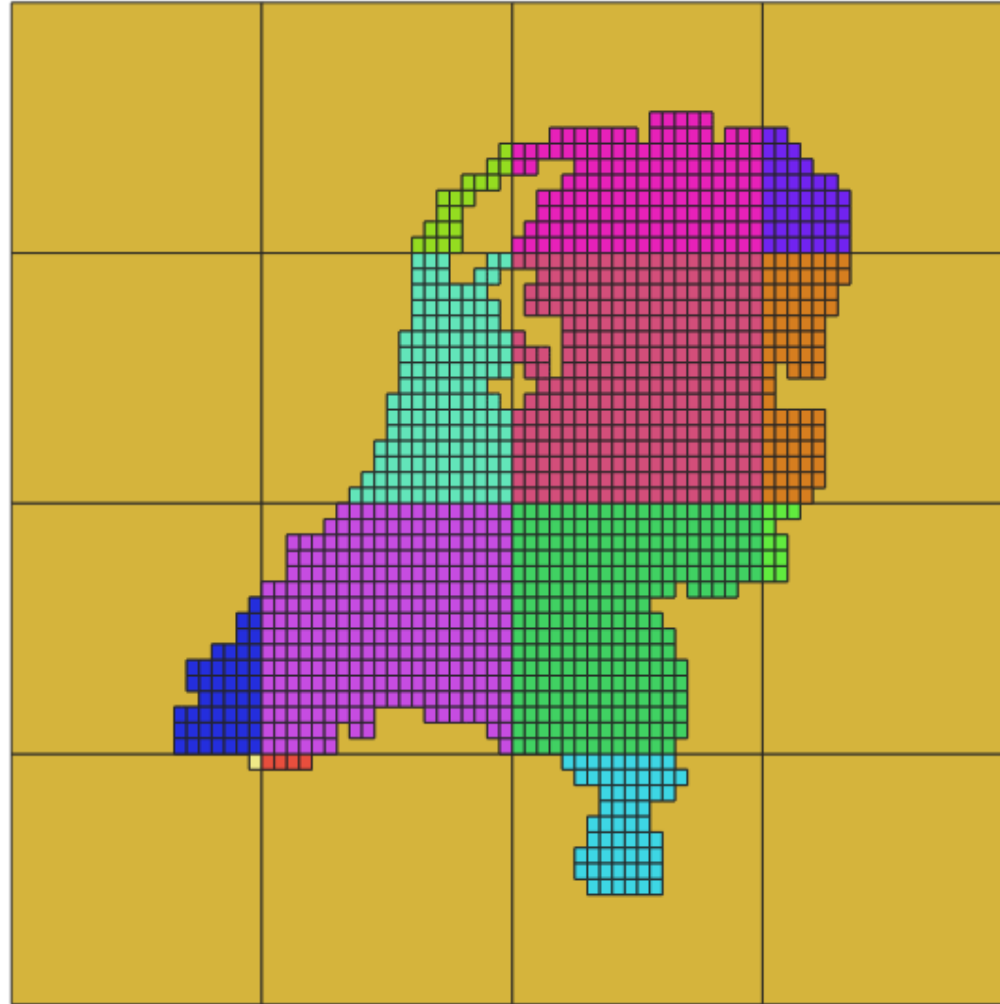
Performance

- Perfect overlap in copying/removing data and processing in distribution and indexing phase.

-  **Copy a partition**
-  **Remove partition**
-  **Move partial output to “BIG” storage**
-  **Distribution and Indexing**



Limitations



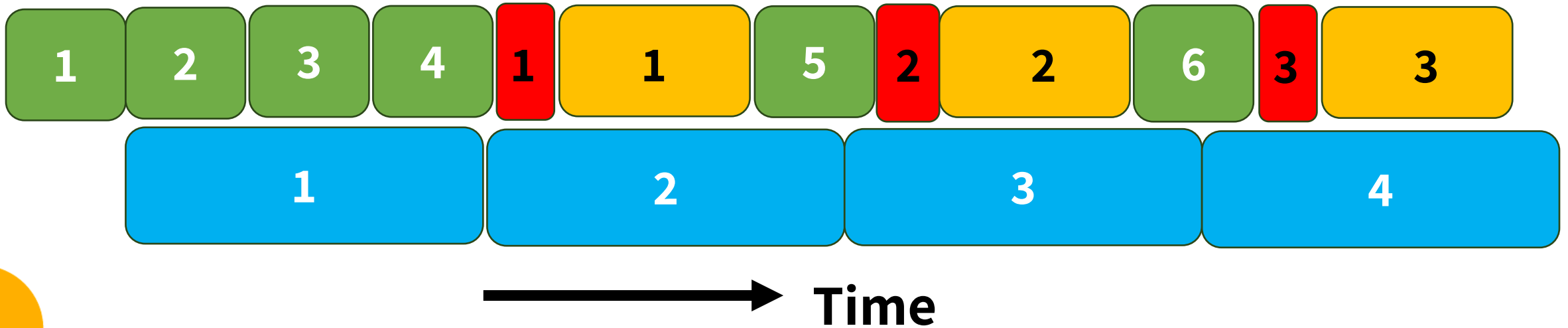
Limitations

- The implementation is 6-7x slower than ideal.
 - Investigating. May be due to shared scratch space. Copying the data to local SSD per node may help



Further Improvements

- Copy a partition
- Remove partition
- Move partial output to “BIG” storage
- **Counting, Distribution and Indexing**



Target

"An implementation that works on a laptop to a cluster irrespective of the input data size."



Questions and Suggestions?



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